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Need for Speed Fast Timing for HEP Experiments

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U.S. DEPARTMENT OF
ENERGY

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Materials and Acknowledgements

A lot of the material and diagrams in this presentation were prepared by others:

P. Orel, G. S. Varner: “Femtosecond Resolution Timing in Multi-GS/s Waveform Digitizing ASICs”
IEEE Transactions on Nuclear Science (Volume: 64, Issue: 7, July 2017)

N Cartiglia: “Signal formation and timing with LGAD sensors” (various presentations)

N. Cartiglia: “Why shot noise in LGAD does not degrade time resolution?” (AIDA 2020 meeting 2019)

W. Riegler, G. Aglieri Rinella: “Time resolution of silicon pixel sensors”
JINST 12 P11017 (arxiv: <https://arxiv.org/abs/1706.04883>)

N. Cartiglia et al: “4D tracking: present status and perspectives”
NIM A Volume 1040, 1 October 2022, 167228 (arxiv: <https://arxiv.org/abs/2204.06536>)

N. Cartiglia et al: “An Introduction to Ultra-Fast Silicon Detectors”
CRC Press

Presentations from Zhenyu Ye, Alexander Kiselev, Jennifer Ott and others at CPAD 2024 here at UTK!

Timing in HEP – Current and Future

Every large HEP experiment is currently working on a super fast timing upgrades.

Every planned future HEP (and adjacent) experiment is planning for super fast timing capabilities.

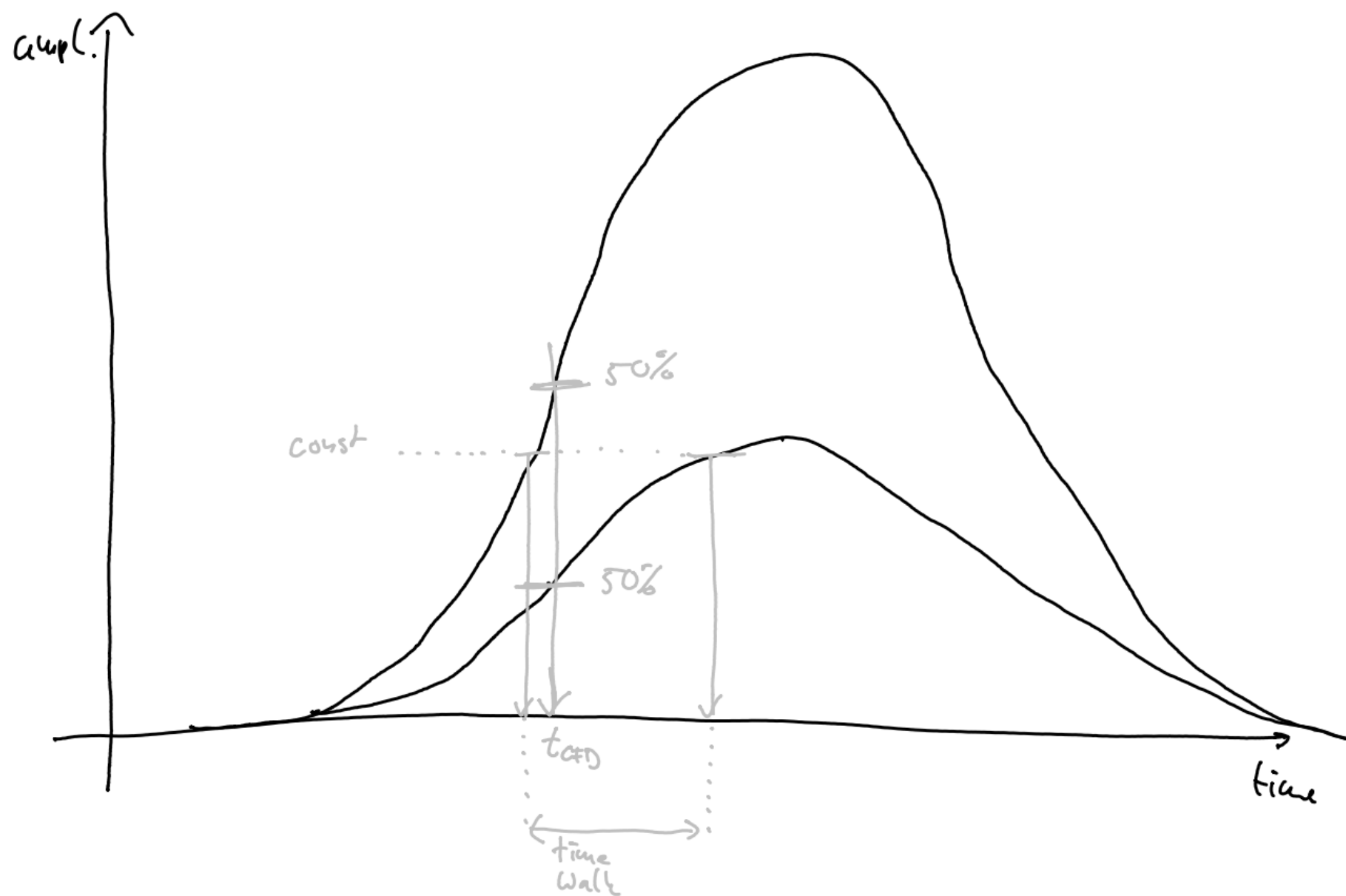
Timing is everything.



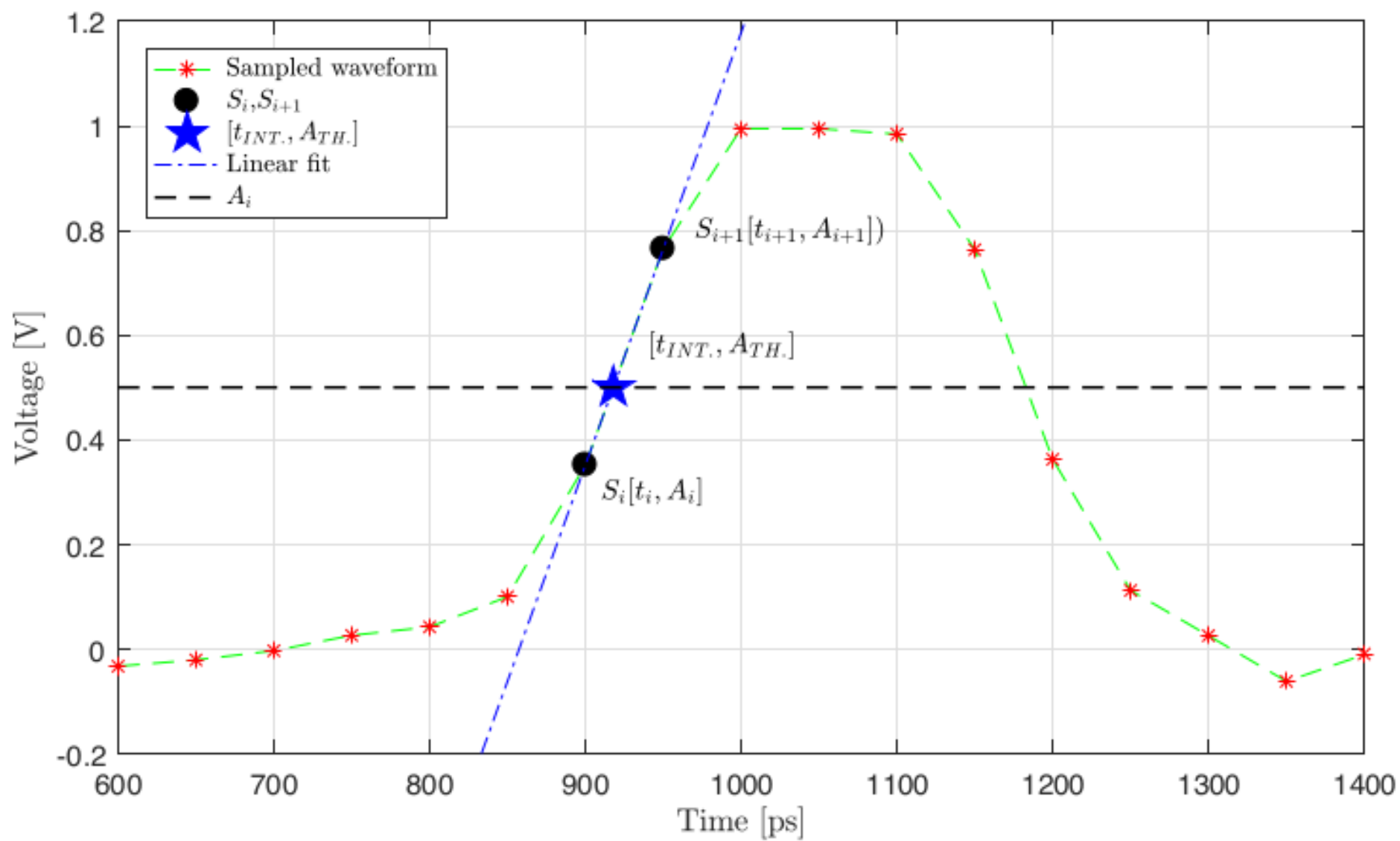
Timing

Given some signal, at which time did it occur?

Timing



Timing



Timing

Given some signal: at which time did it occur?

Constant threshold

Needs timewalk correction from amplitude measurement

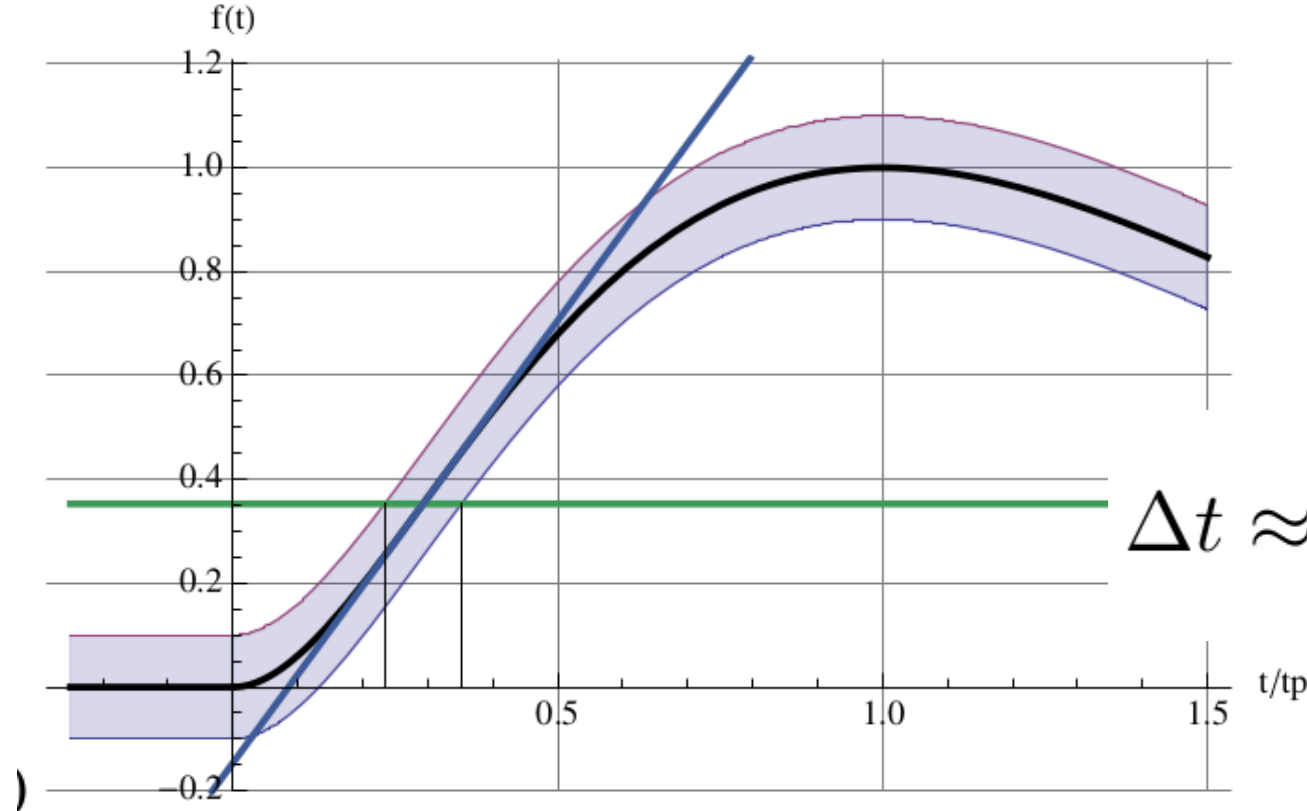
Constant fraction

Can be done in analog circuitry (how?)

Can be done “digitally” from waveform sampling

Timing Uncertainty

Amplitude noise yields timing uncertainty

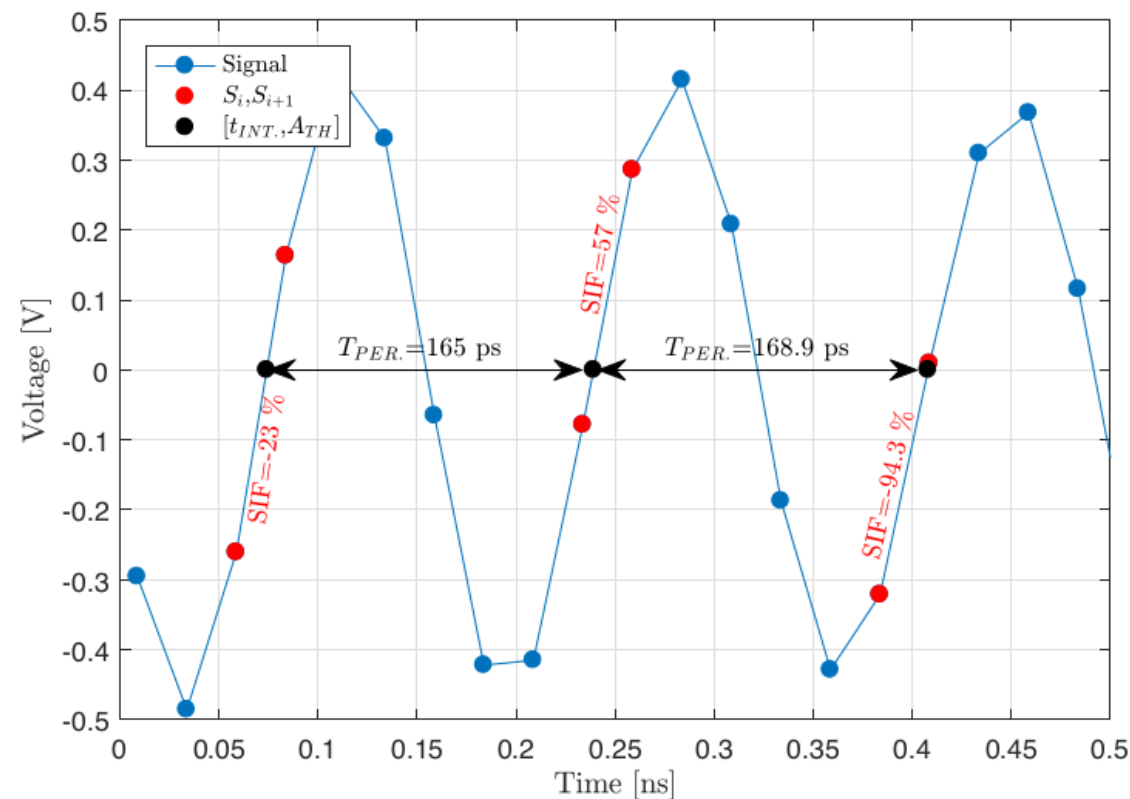


$$\Delta t \approx \frac{\Delta u}{U} \frac{1}{\sqrt{3 f_{SAMP} BW}}$$

Just sample faster?

Just increasing sampling speed will not help much if using two points:

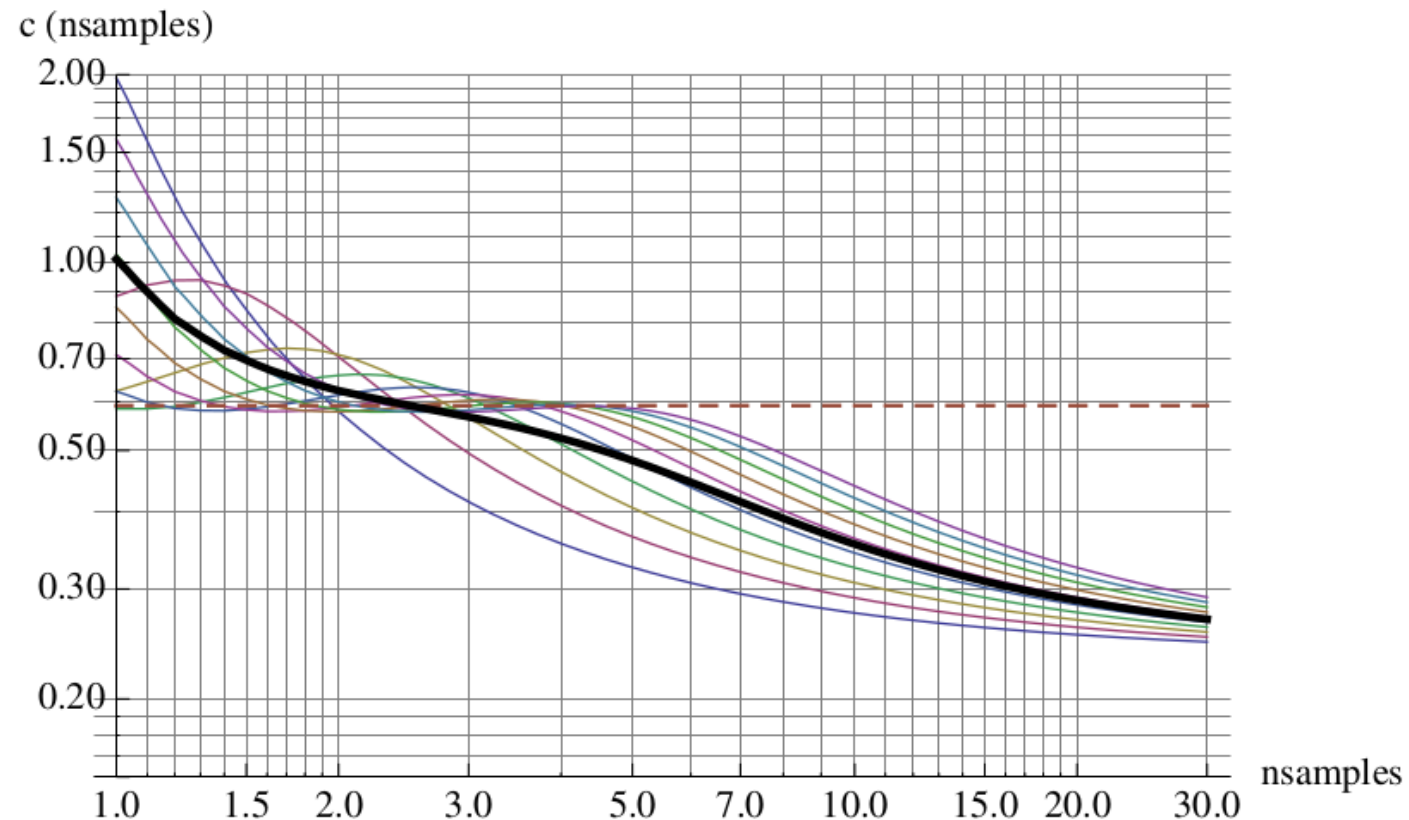
Noise of two points will always contribute
Sometimes even dominated by full noise of single sample



Just sample faster?

Template transient fit over several points will help

Needs very fast sampling and excellent understanding of signal shapes
Somewhat mediocre returns....



Instead: Improve Signal-to-Noise Ratio (SNR)

Timing uncertainty scales with peaking time t_p :

$$\begin{aligned}\sigma_t &= \frac{\sigma_{\text{noise}}}{A} t_p \times (0.59, 0.57, 0.54, 0.51) & \text{for } n = 2, 3, 4, 5 \\ &= \frac{\sigma_{\text{noise}}}{A} \frac{1}{f_{\text{bw}}} \times (0.10, 0.12, 0.13, 0.14) & \text{for } n = 2, 3, 4, 5\end{aligned}$$

Series noise of any amplifier scales with $1/\sqrt{t_p}$:

$$\sigma_{\text{noise}}^2 = \frac{1}{2} e_n^2 C^2 \int_{-\infty}^{\infty} f'(t)^2 dt = \frac{1}{2} e_n^2 C^2 \frac{n^2 (2n-2)!}{t_p} \left(\frac{e}{2n} \right)^{2n}$$

Go for very short peaking time, increase dV/dt

use the best amplifier you can afford (in power budget)

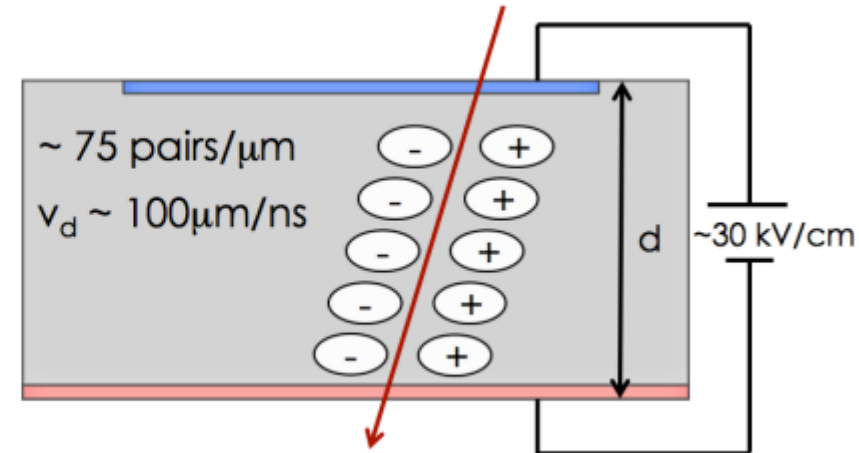
Timing in Silicon Sensors

Signal Formation in Silicon

We need a large, fast signal.

What is controlling
the slew rate?

$$\frac{dV}{dt} \propto ?$$

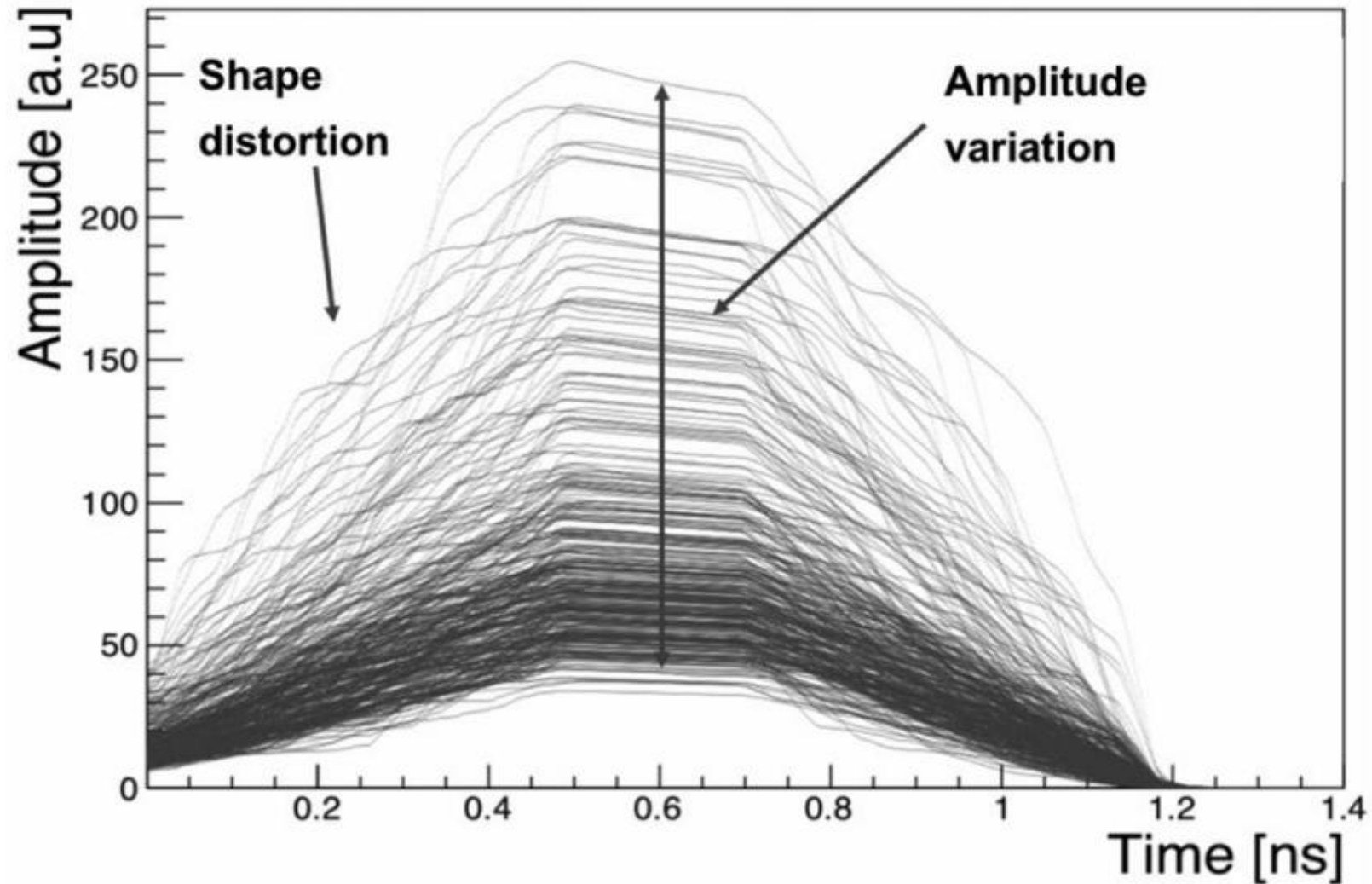


Separated charges start moving inside silicon bulk under influence of electric field

Motion of charges induces a current on electrodes (**not** charges reaching electrodes!)

Signal ends when charges reach the electrode

Signal Shape Distortions



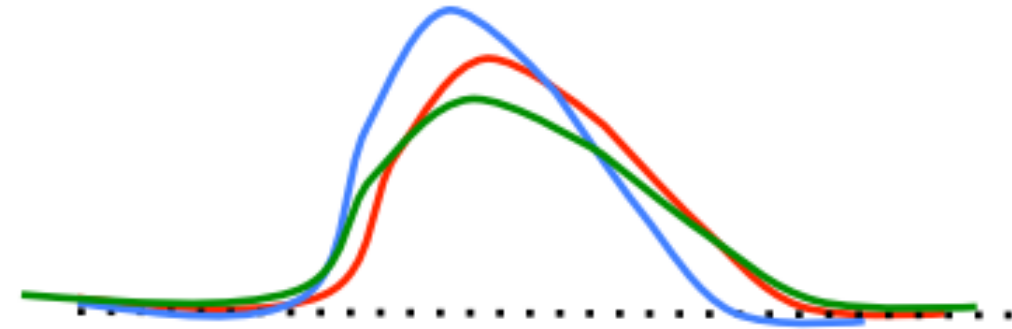
How to get a nice signal? – a little bit of Shockley-Ramo

Signal uniformity is key!

$$i \propto qvE_w$$

Drift velocity

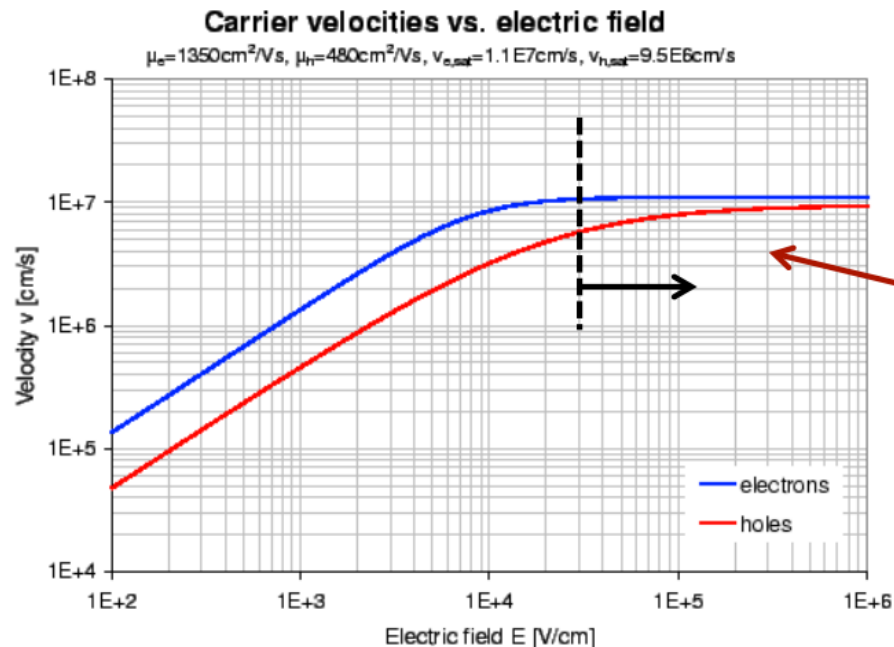
Weighting field



Drift Velocity

$$i \propto q \underbrace{v}_w E$$

- Highest possible E field to saturate velocity
- Highest possible resistivity for velocity uniformity



We want to operate in this regime

Figure: Electron and hole velocities vs. the electric field strength in silicon.

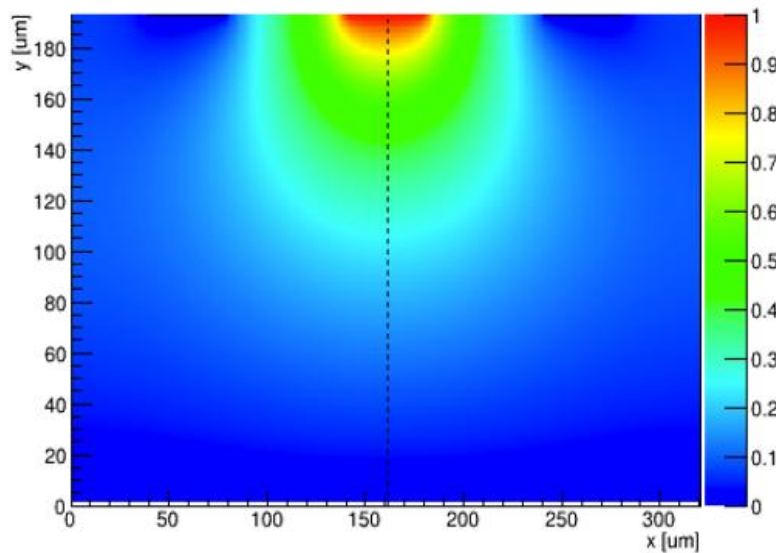
Weighting Field

Need uniform weighting field

Entirely depends on diode geometry

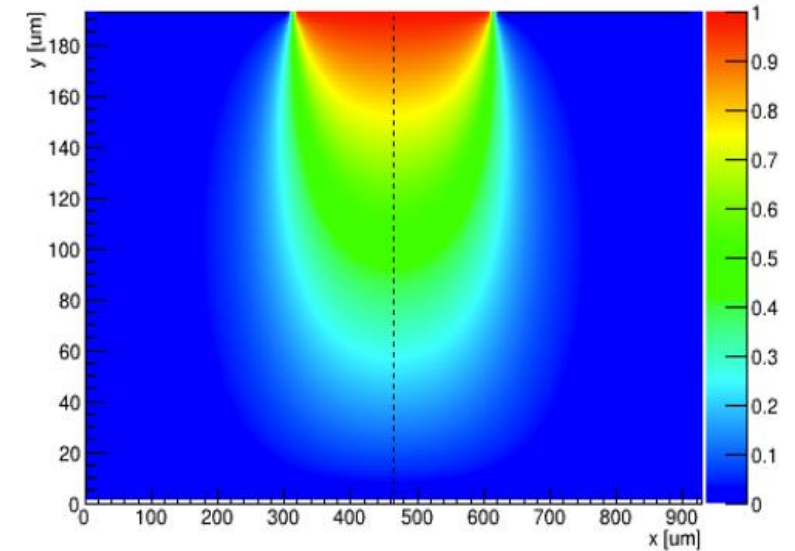
$$i \propto qvE_w$$

Strip: 100 μm pitch, 40 μm width



Bad: almost no coupling away from the electrode

Pixel: 300 μm pitch, 290 μm width



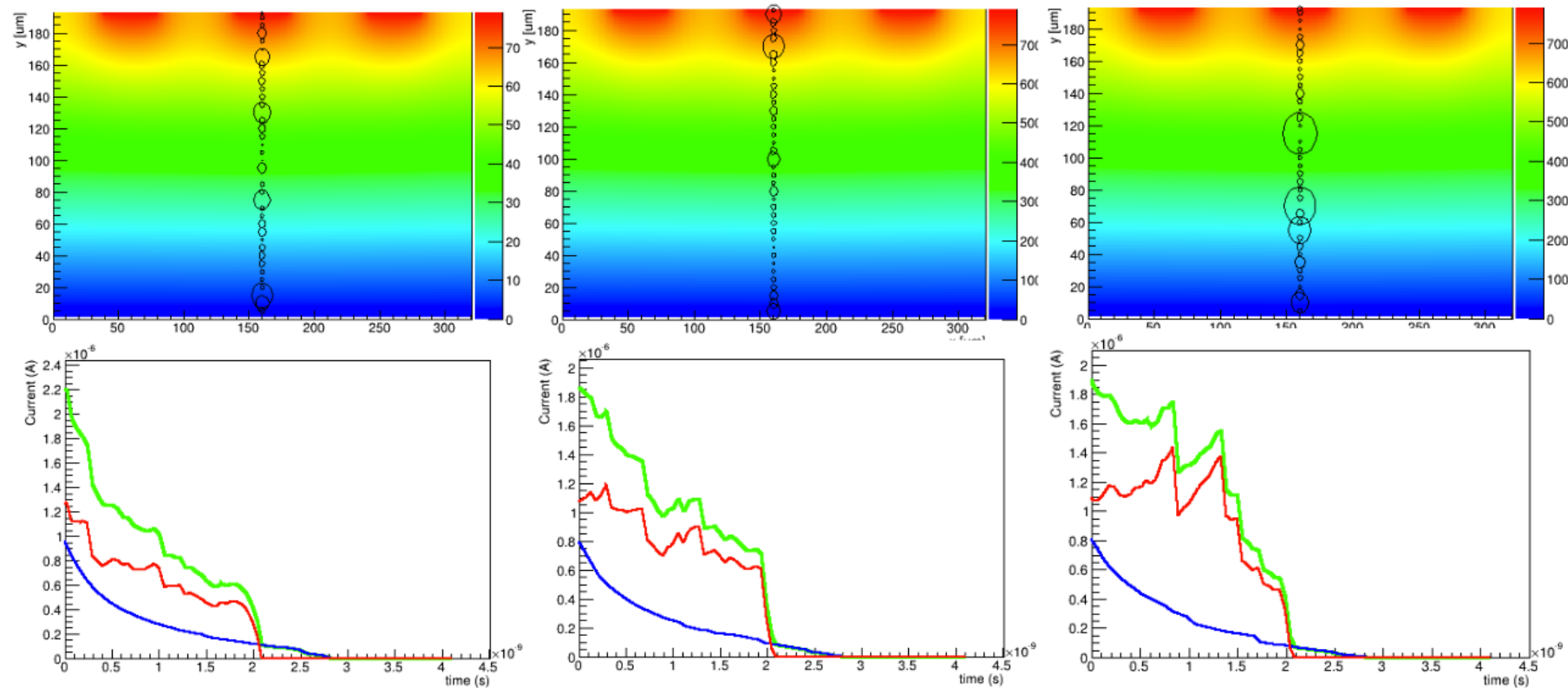
Good: strong coupling almost all the way to the backplane

Non-uniform depositions

Landau fluctuations

cause amplitude variation – corrected by timewalk/CFD

cause non-uniform charge deposition:

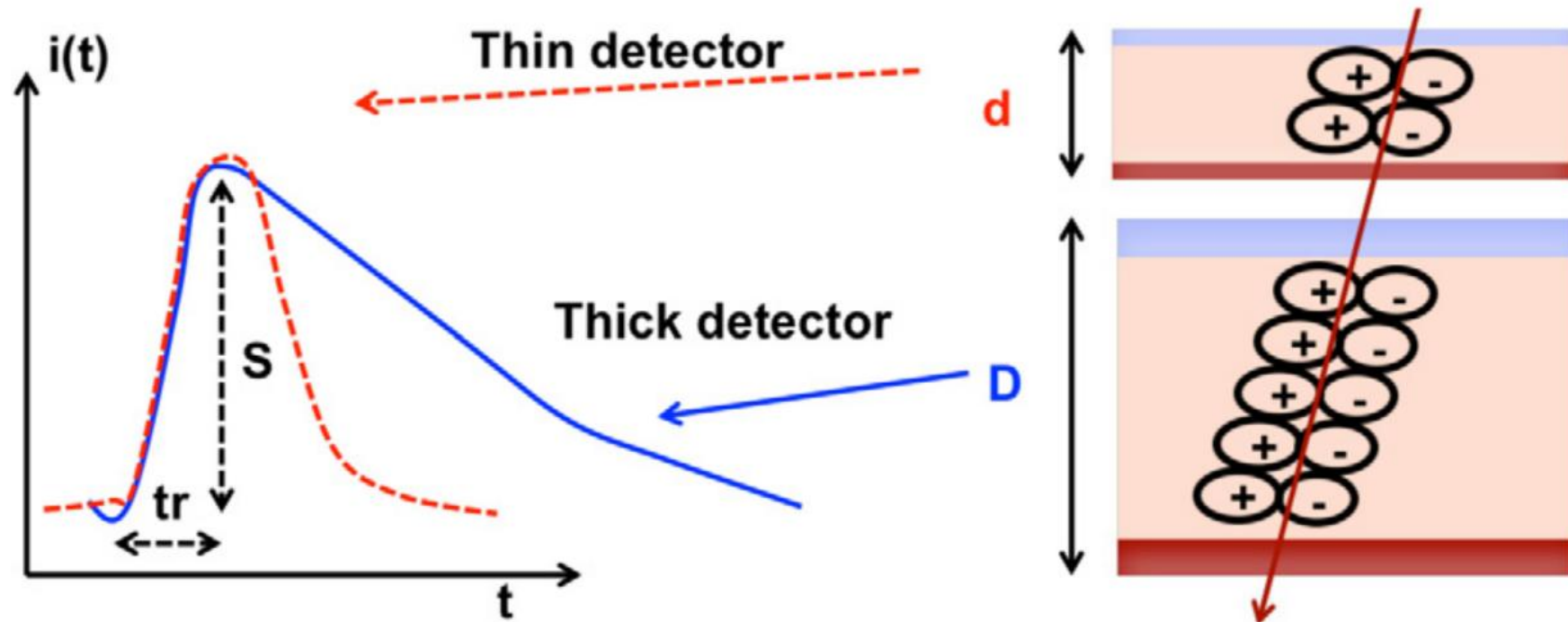


Sensor Thickness

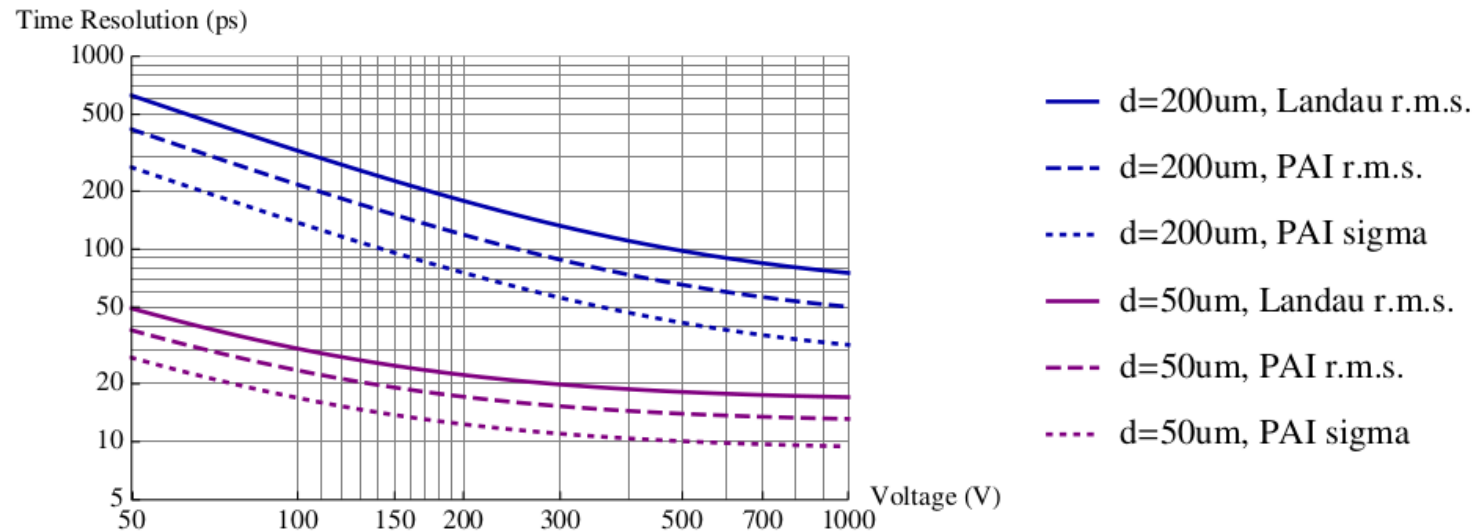
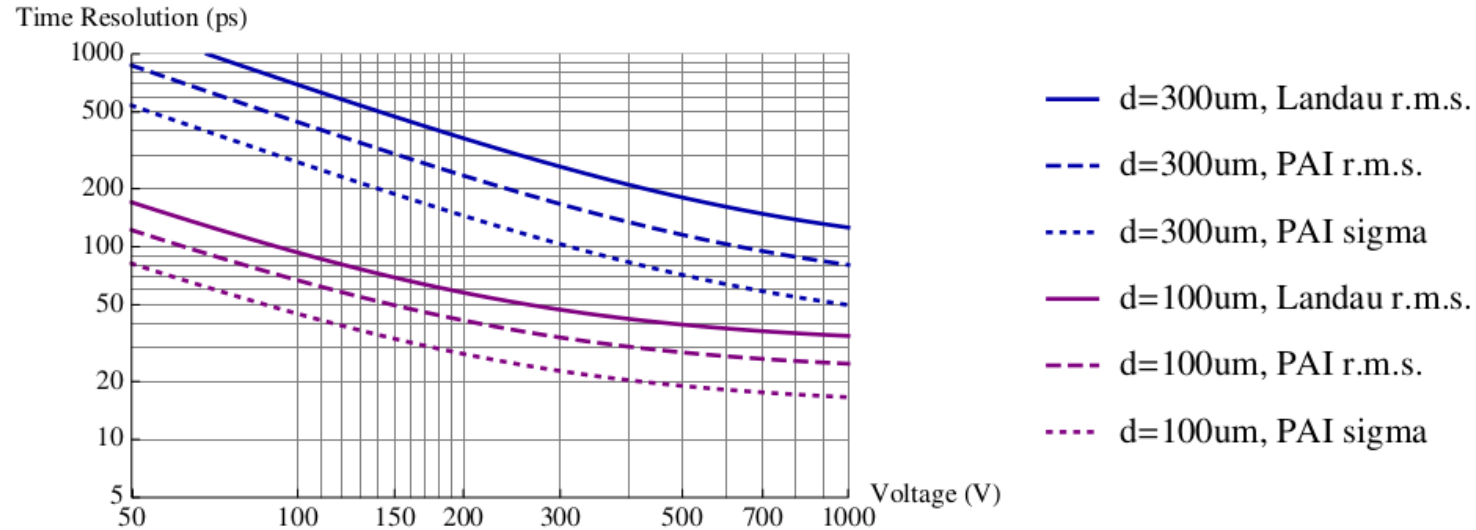
Thicker sensors produce more signal...

...but the initial signal slew rate does not depend on the sensor thickness!

I_{max} in a silicon diode is always $\sim 1.5\mu\text{A}$



Timing in Silicon Sensors – no internal amplification



So What?

Overall silicon sensor time resolution:

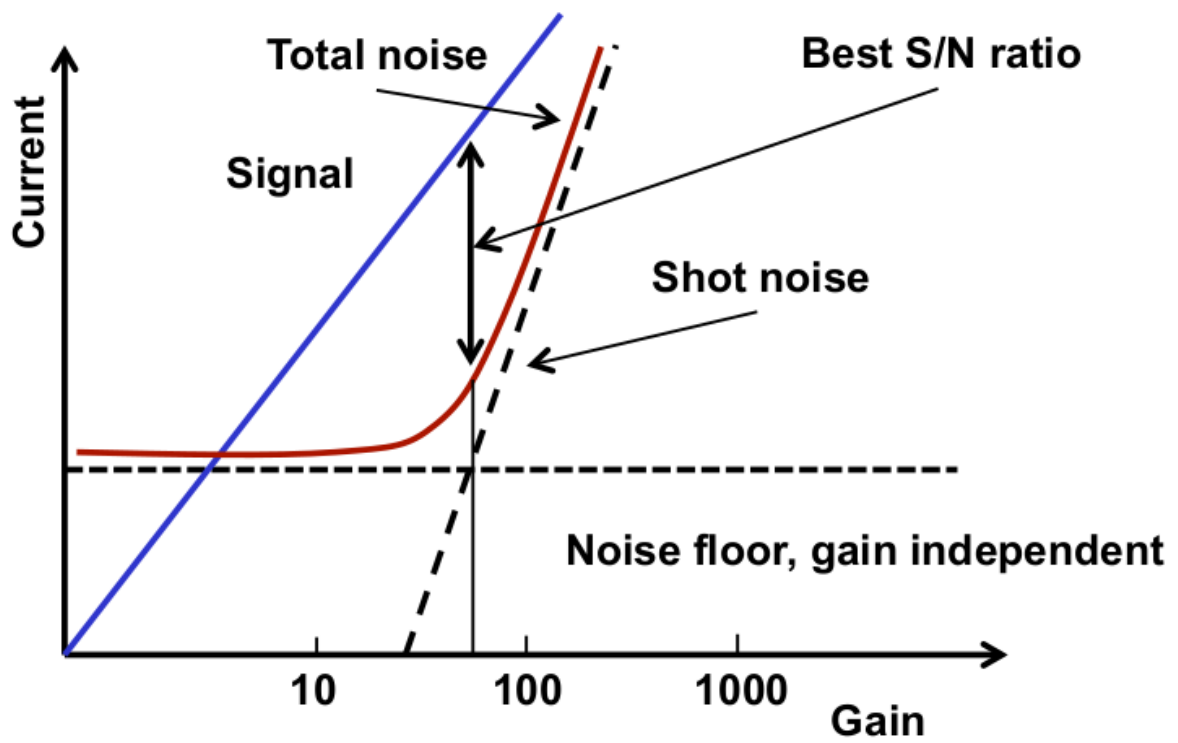
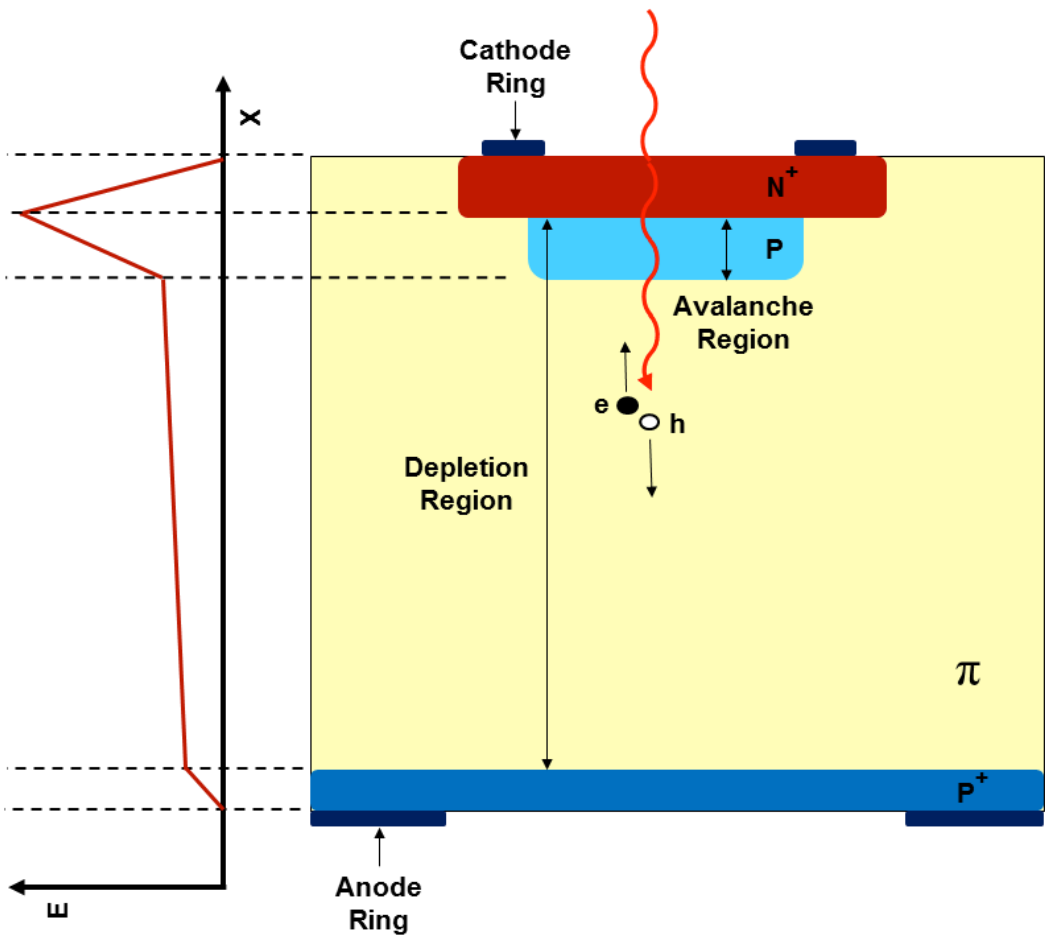
$$\sigma_t^2 = \sigma_{\text{Jitter}}^2 + \sigma_{\text{Ionization}}^2 + \sigma_{\text{Distortion}}^2 + \sigma_{\text{TDC}}^2.$$

Bringing us back to the perfect preamplifier...

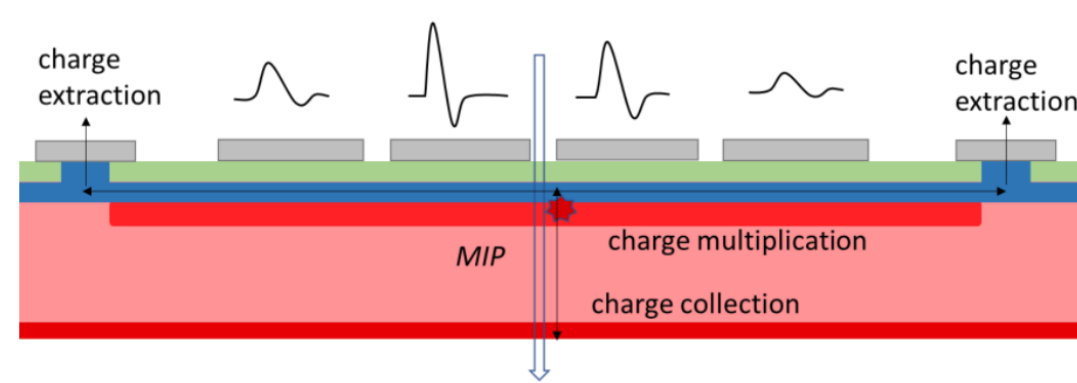
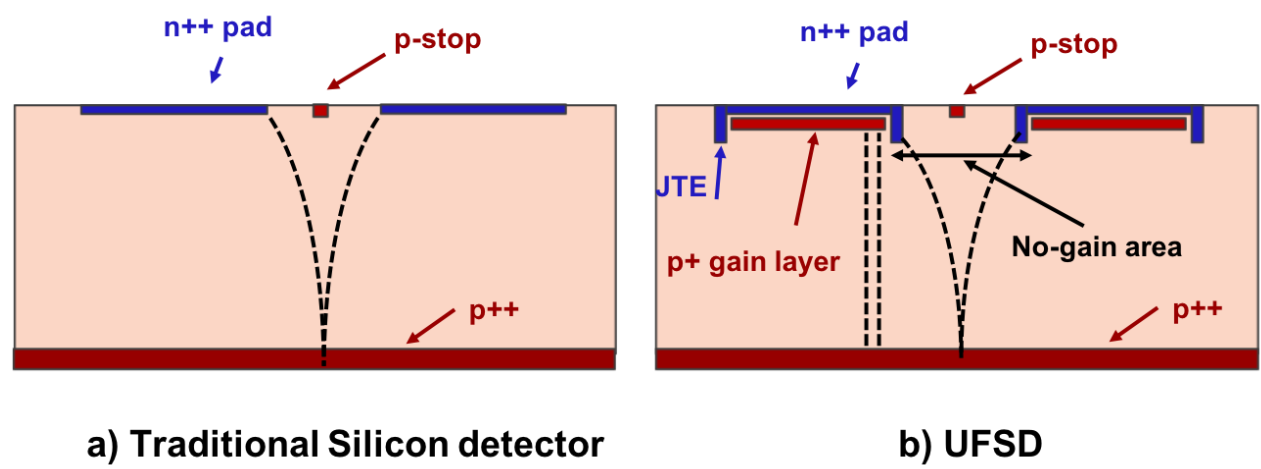
$$\sigma_{\text{Jitter}}^2 = \frac{1}{2} e_n^2 C^2 \int_{-\infty}^{\infty} f'(t)^2 dt = \frac{1}{2} e_n^2 C^2 \frac{n^2 (2n-2)!}{t_p} \left(\frac{e}{2n}\right)^{2n}$$

How about amplifying the signal directly in the sensor?

Amplification in Silicon

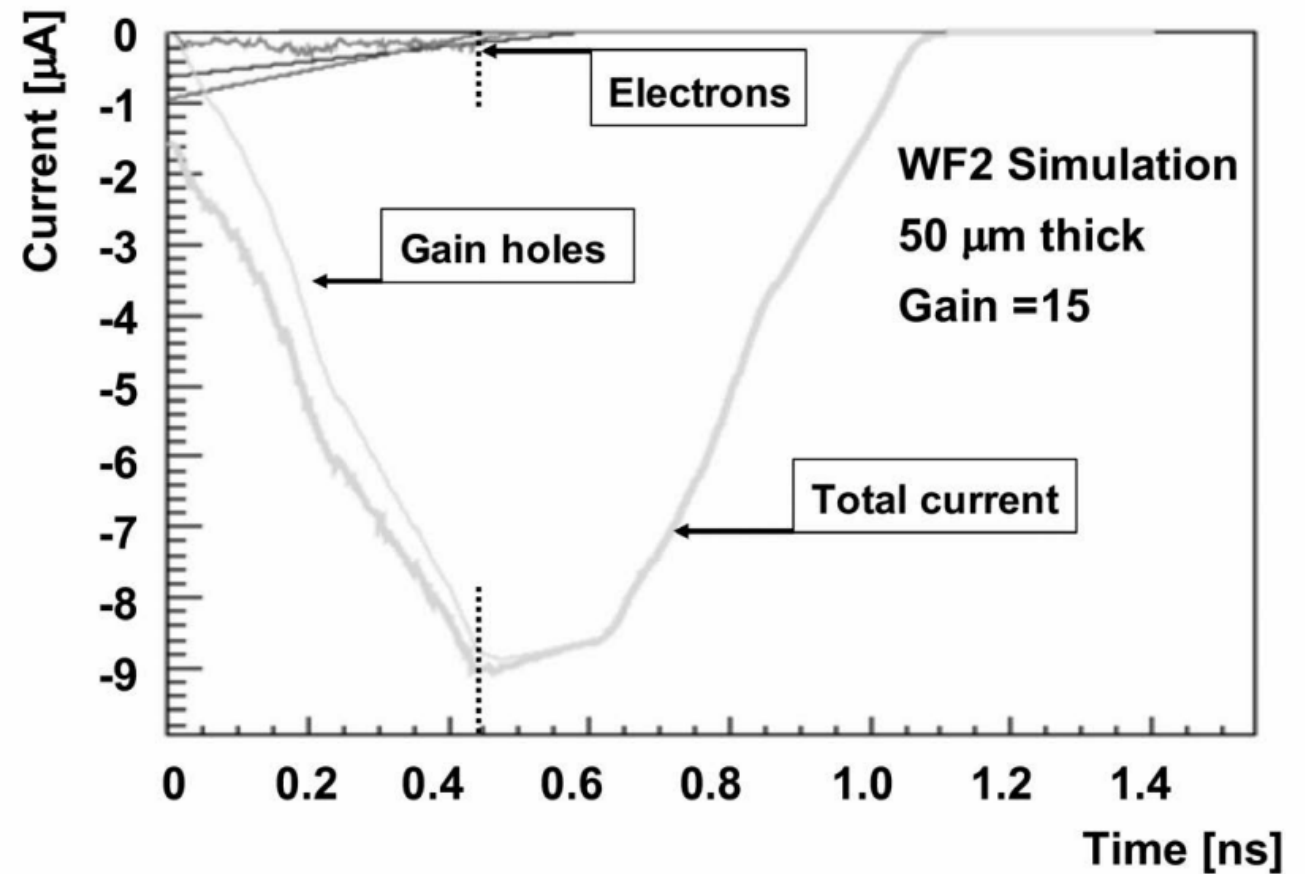


LGADs and AC-LGADs

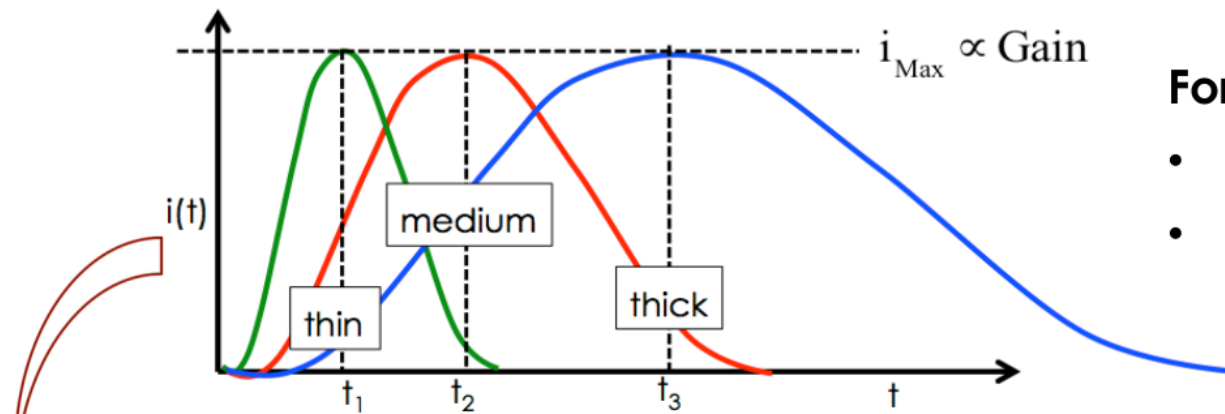


Signals of LGADs

Gain holes always travel full width of silicon
Slew rate now depends on thickness.

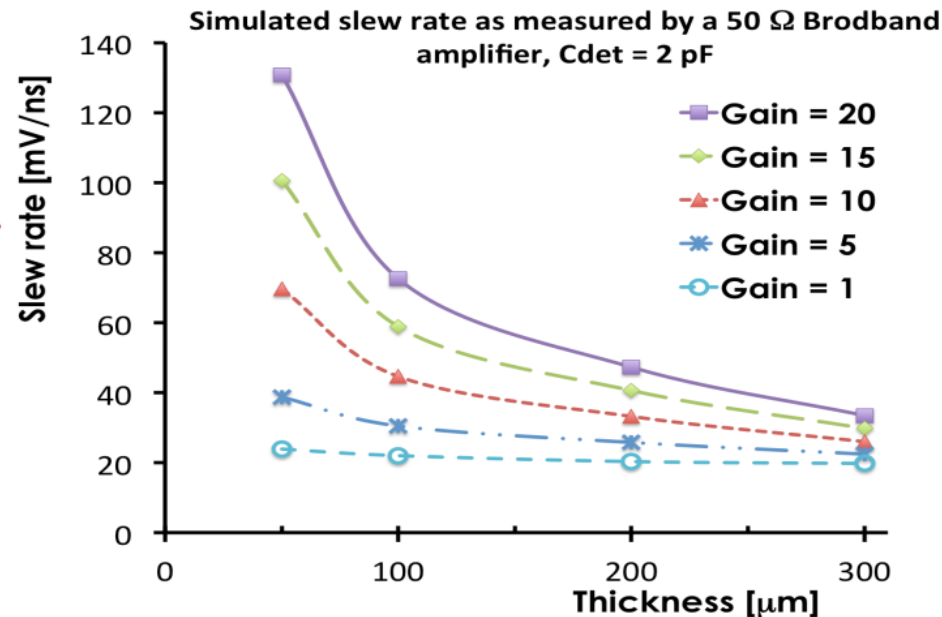


Signals of LGADs



For a fixed gain:

- amplitude = constant
- rise time $\sim 1/\text{thickness}$



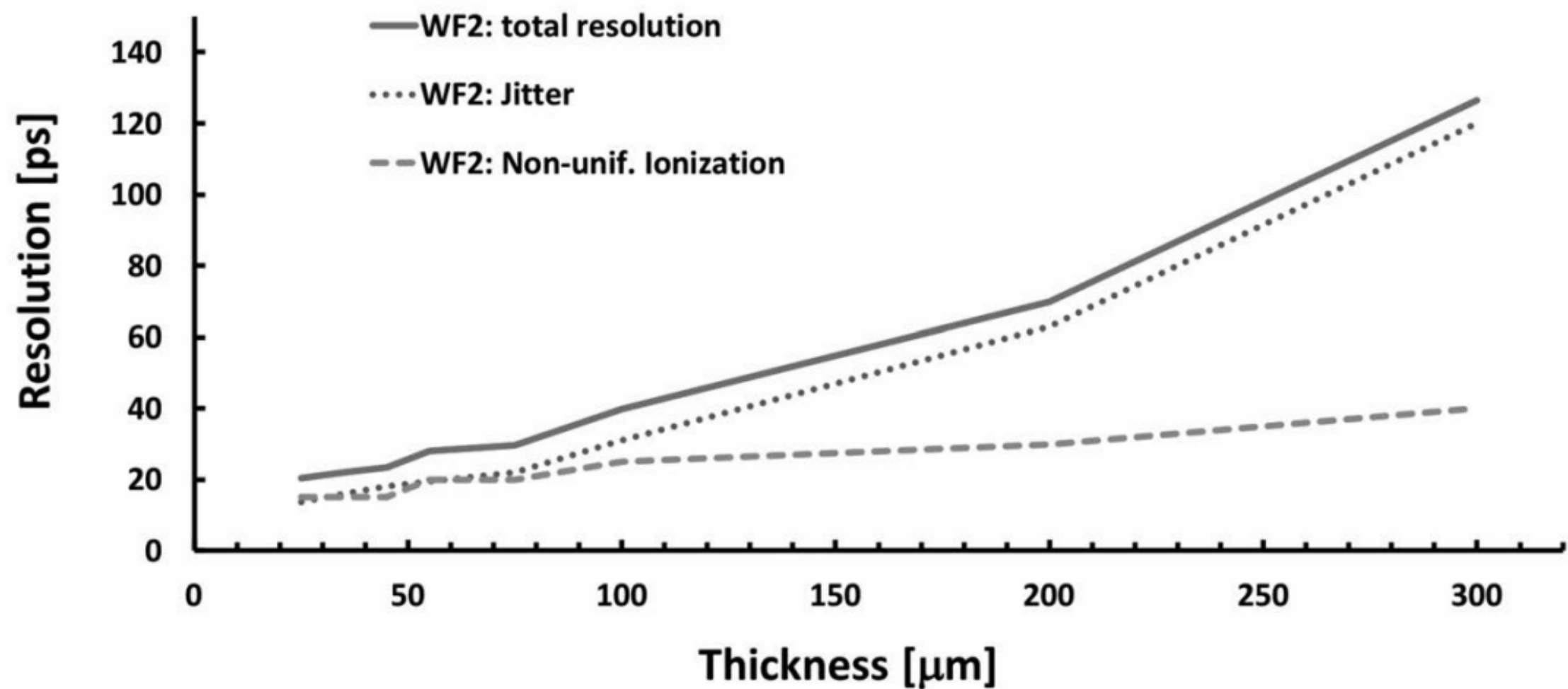
The slew rate:

- Increases with gain
- Increases $\sim 1/\text{thickness}$

$$\frac{dV}{dt} \propto \frac{G}{d}$$

→ Go thin!!

Hitting the Landau Limit



Some Current Applications

Chosen entirely by my personal preference and involvement.

There were dozens of talks on exciting developments and projects for fast timing sensors and detector concepts at CPAD 2024 here at UTK last year, I could not possibly give justice to the field.

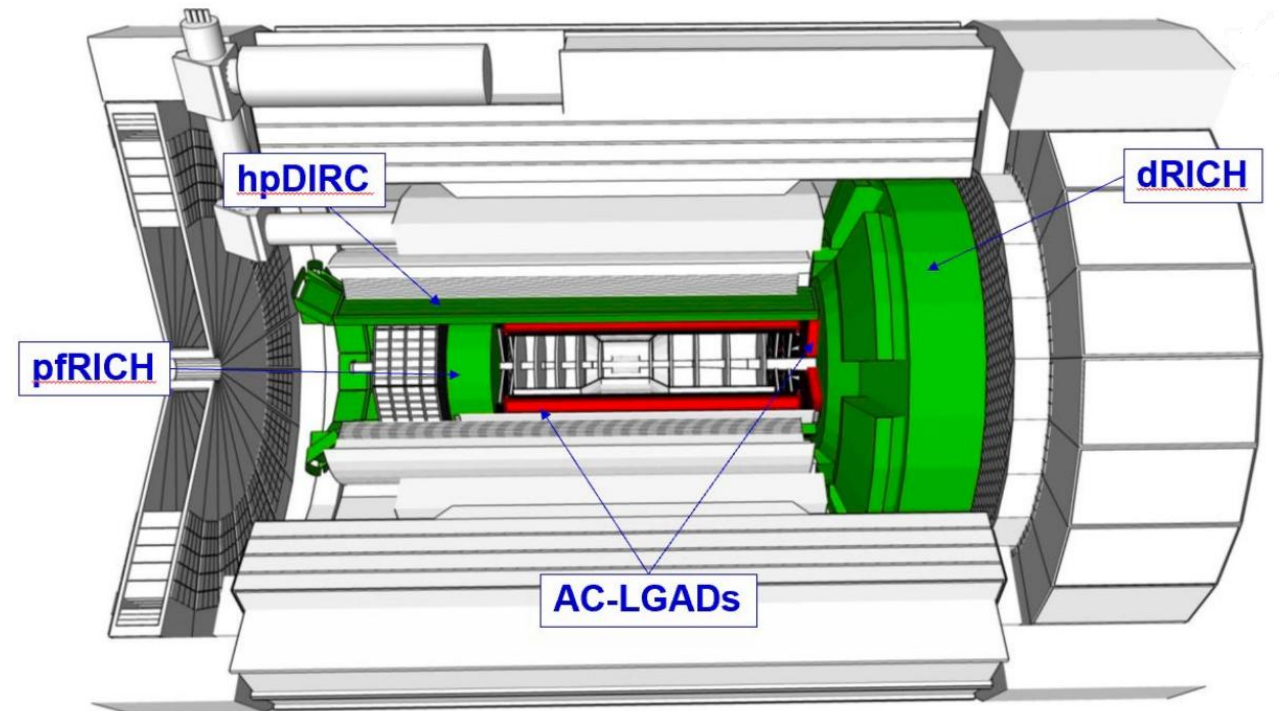
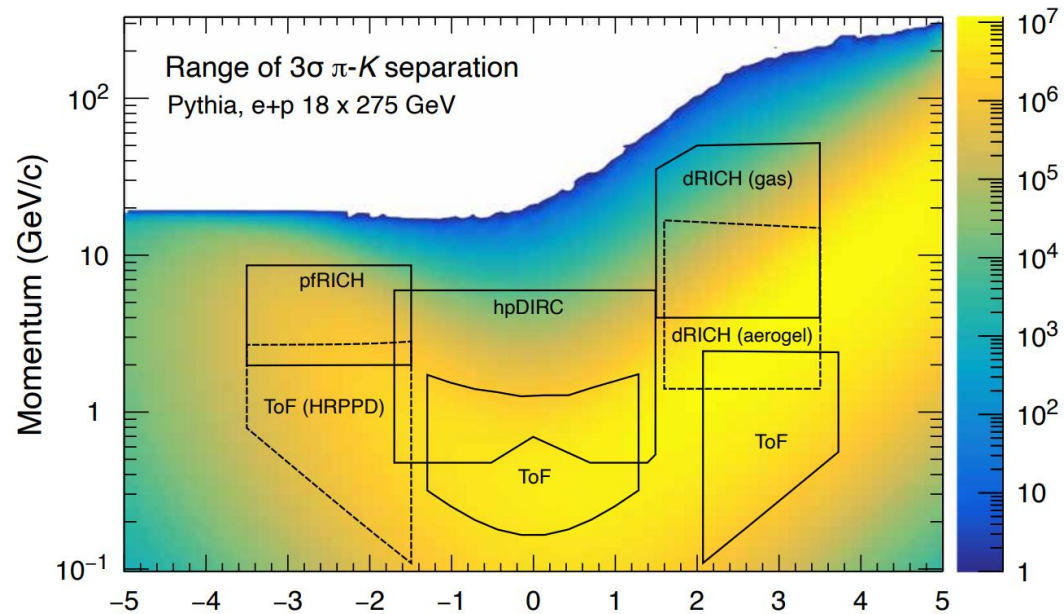
ePIC TOF – AC-LGADs Galore



ePIC is the first detector at the upcoming Electron-Ion Collider at BNL

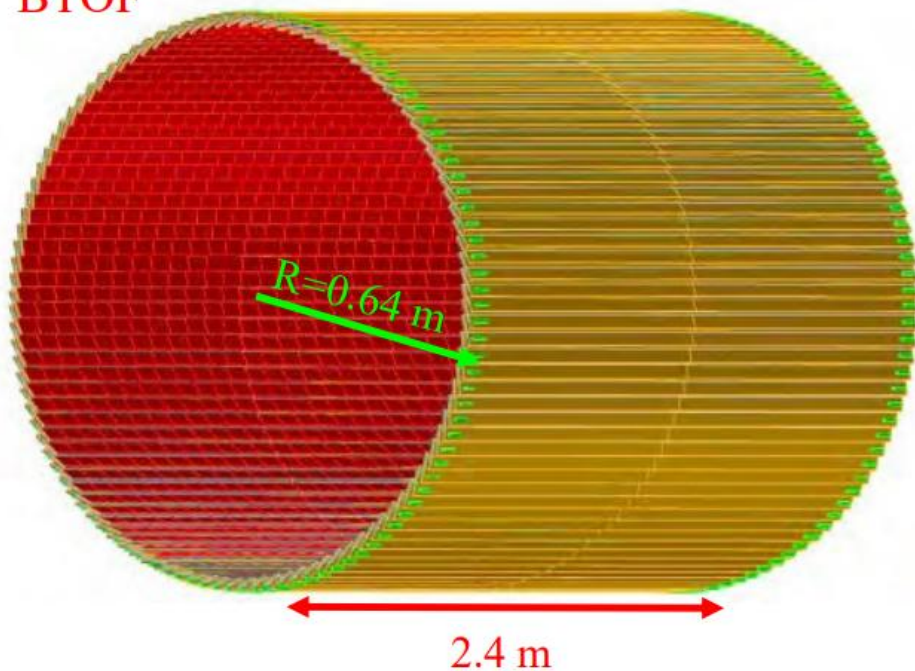
ePIC will unravel the structure of nuclear matter and the QGP

Full PID coverage in full momentum range required

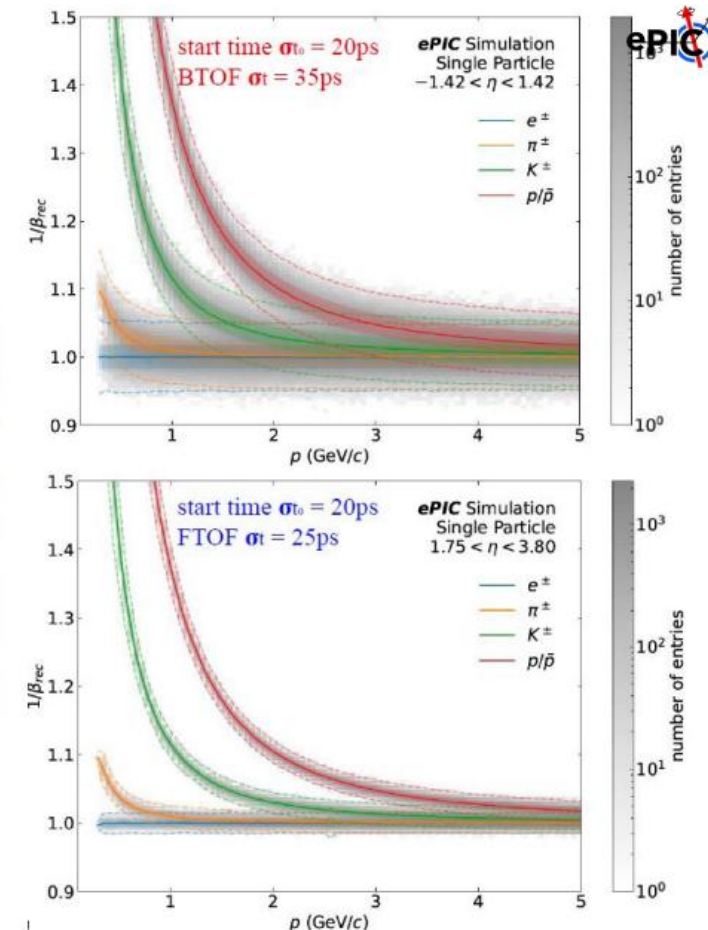
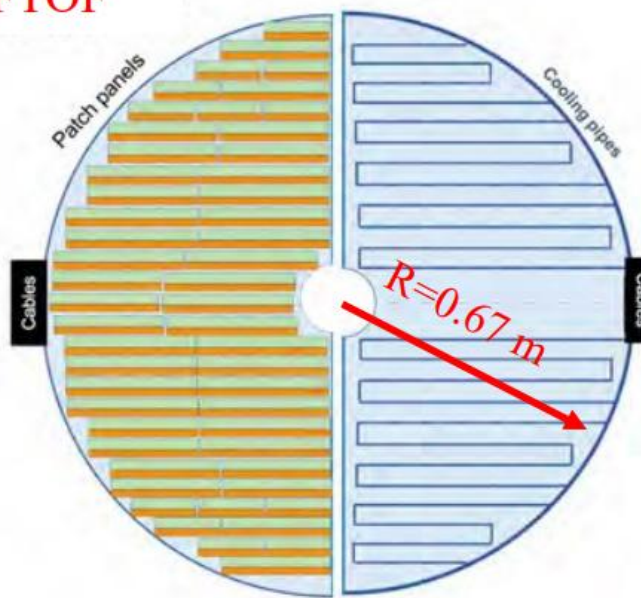


AC-LGAD Detectors for ePIC

BTOF



FTOF

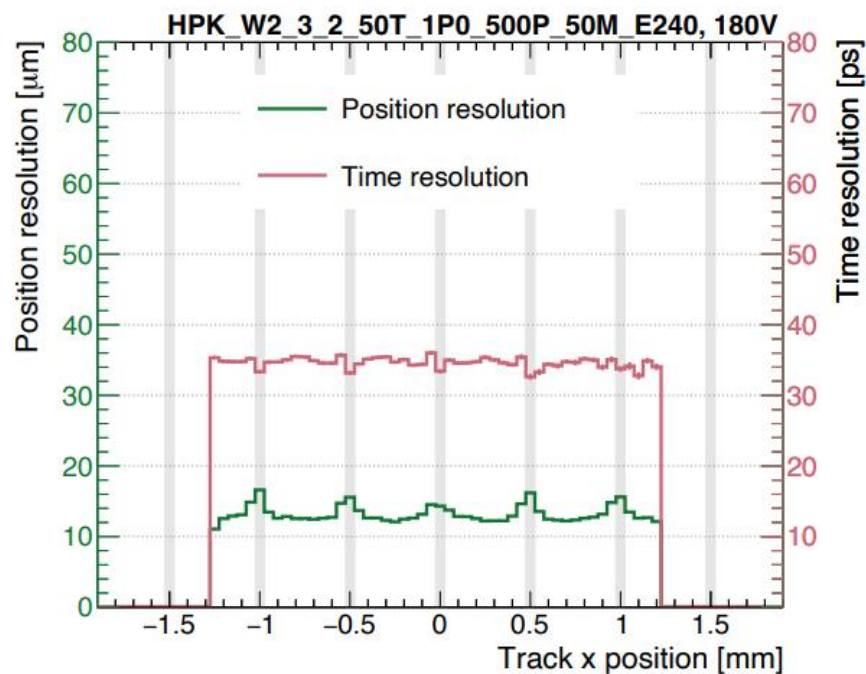
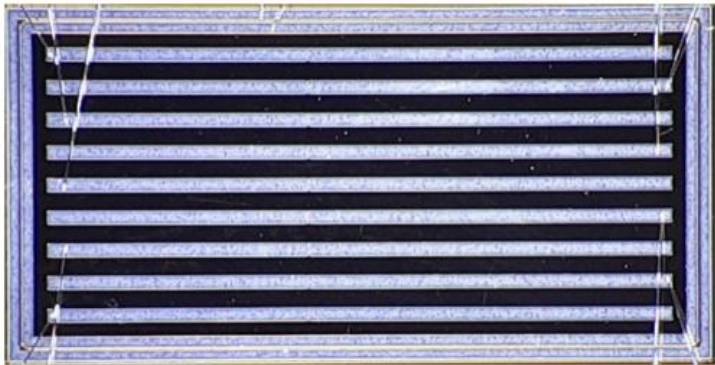


	Area (m ²)	Channel size (mm ²)	# of Channels	Timing Resolution	Spatial resolution	Material budget
Barrel TOF	10	0.5*10	2.4M	35 ps	30 μm in $r \cdot \varphi$	0.01 X_0
Forward TOF	1.4	0.5*0.5	5.6M	25 ps	30 μm in x and y	0.05 X_0
B0 tracker	0.07	0.5*0.5	0.28M	30 ps	20 μm in x and y	0.05 X_0
RPs/OMD	0.14/0.08	0.5*0.5	0.56M/0.32M	30 ps	140 μm in x and y	no strict req.

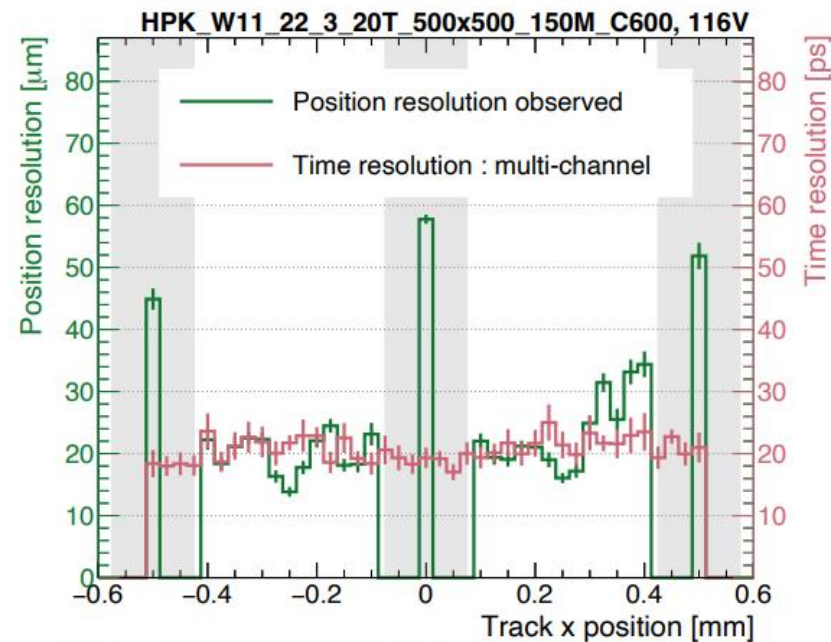
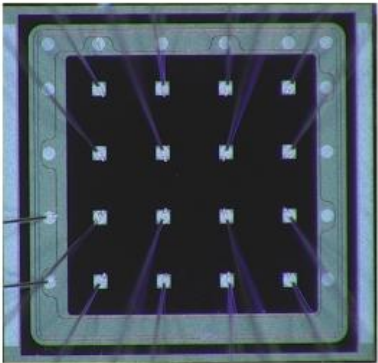
ePIC TOF Sensor Tests

Chosen entirely b
There were doze
concepts atCPAL

HPK Strip Sensor (4.5x10 mm²)

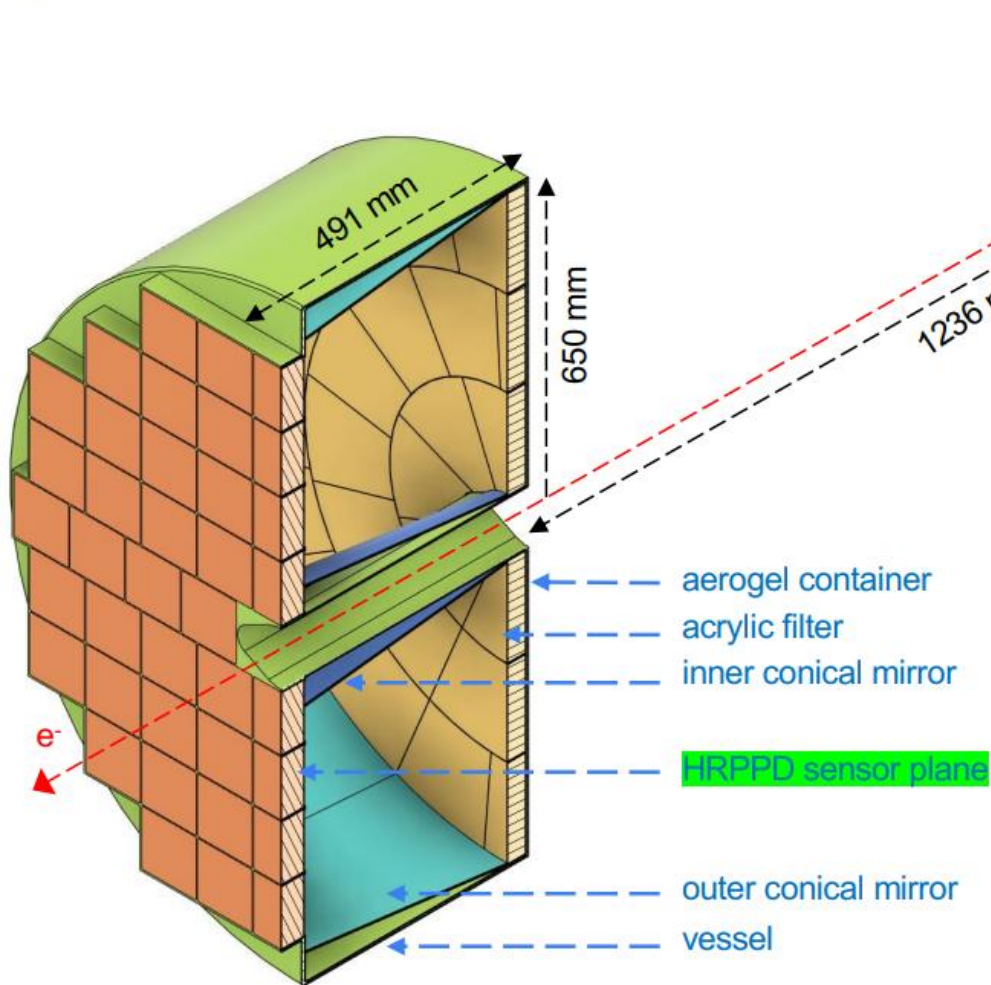


HPK Pixel Sensor (2x2 mm²)



Bonus: what about the ePIC backward TOF?

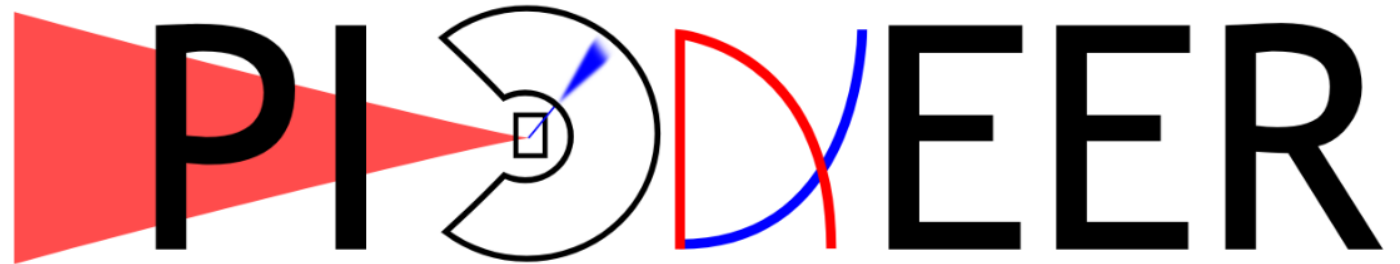
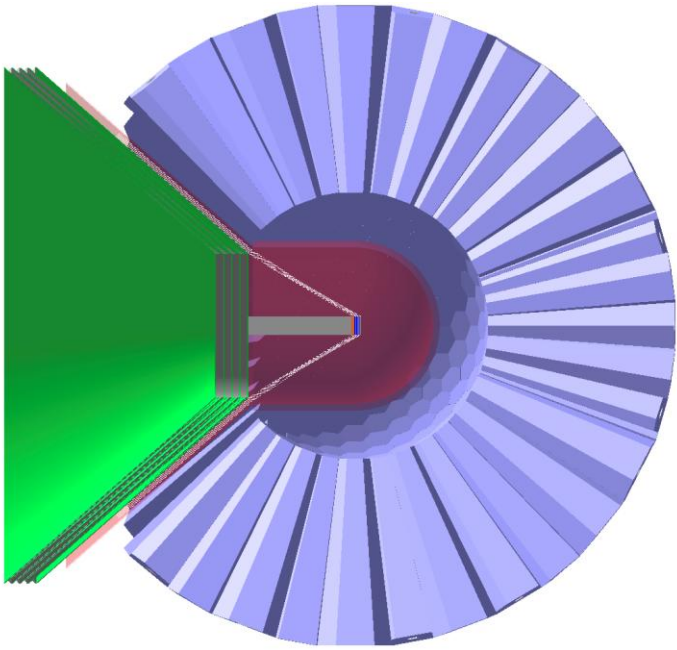
pfRICH for ePIC detector electron-going endcap



- A classical proximity focusing RICH
 - with a high-resolution timing capability
- Pseudorapidity coverage: $-3.5 < \eta < -1.5$
- Uniform performance in this $\{\eta, \phi\}$ range
- $< 20 \text{ ps}$ t_0 reference for the ToF subsystems
- $> 3\sigma$ π/K separation up to $\sim 7.0 \text{ GeV}/c$
- $\sim 100\%$ geometric efficiency

Alexander Kiselev, BNL

PIONEER – The first full 5D AC-LGAD tracker?



A next generation rare pion decay experiment

Physics Case I: Precision Test of Lepton Flavor Universality

Lepton universality:

- Gauge coupling the same for all flavors
- PIONEER will test this fundamental principle to 0.01%

Pion decay ratio $R_{e/\mu} = \frac{\Gamma(\pi \rightarrow e \nu(\gamma))}{\Gamma(\pi \rightarrow \mu \nu(\gamma))}$

- provides unique opportunity

$$R_{e/\mu}(Exp) = 1.23270(230) \times 10^{-4} \quad (0.18\%)$$

$$R_{e/\mu}(SM) = 1.23524(015) \times 10^{-4} \quad (0.01\%)$$

PIENU at TRIUMF
Cirigliano & Rosell

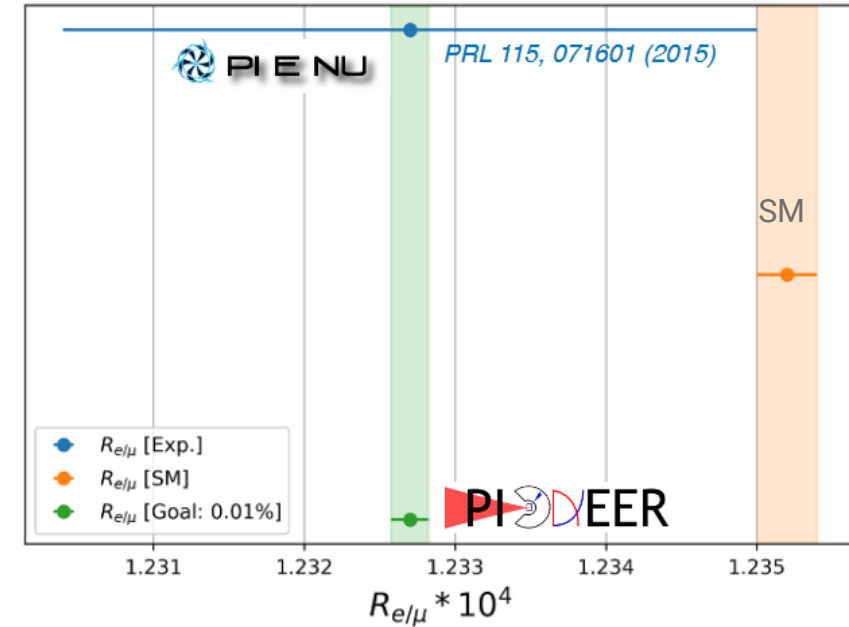
$$\frac{g_\mu}{g_e} = 1.0010 \pm 0.0009$$

- Note:

- Very high precision SM prediction*), theory 15x more precise than experiment
- Strong helicity suppression

- *) 0.01 % uncertainty in NNLO EFT calculation of EW corrections

- PIONEER goal (Phase I)



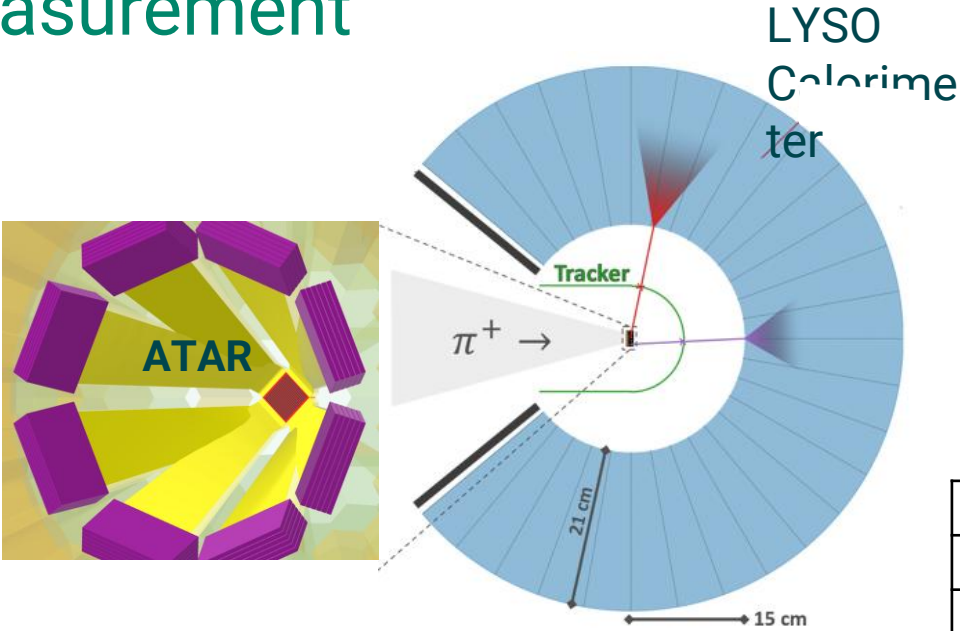
- PIONEER physics reach

- unprecedented LFU sensitivity
0.01% territory
- many BSM scenarios exist
 - $Wl\nu$ coupling, 4-fermion operators
- sensitive to high (PeV) mass scales
 - pseudoscalar, scalar

Basics of $R_{e/\mu} = \frac{\Gamma(\pi \rightarrow e \nu(\gamma))}{\Gamma(\pi \rightarrow \mu \nu(\gamma))}$ measurement

Pion stops in the target

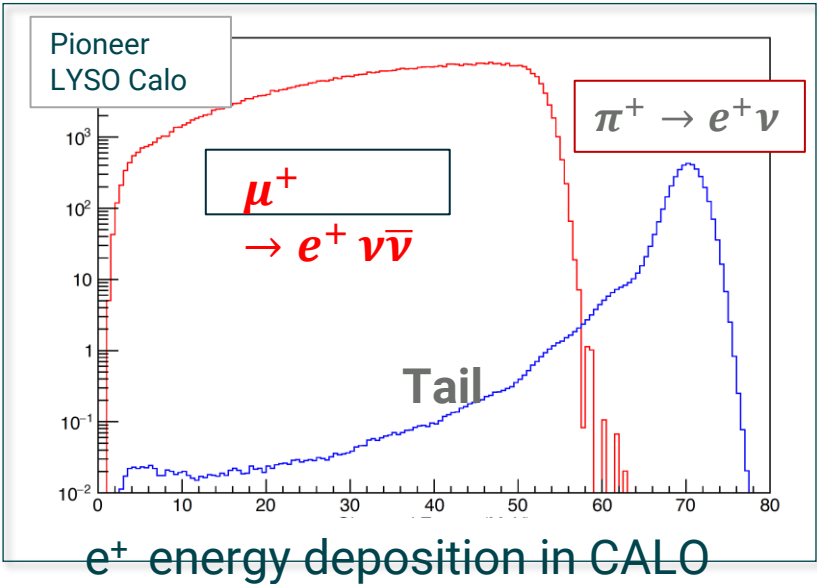
- $\pi^+ \rightarrow \mu^+ \nu(\gamma)$ **99.99%**
 $\mu^+ \rightarrow e^+ \nu \bar{\nu}(\gamma)$ **100 %**
- $E_e = 0.5-52.8 \text{ MeV}$
- $\pi^+ \rightarrow e^+ \nu(\gamma)$ **1.23×10^{-4}**
- $E_e = 69.8 \text{ MeV}$



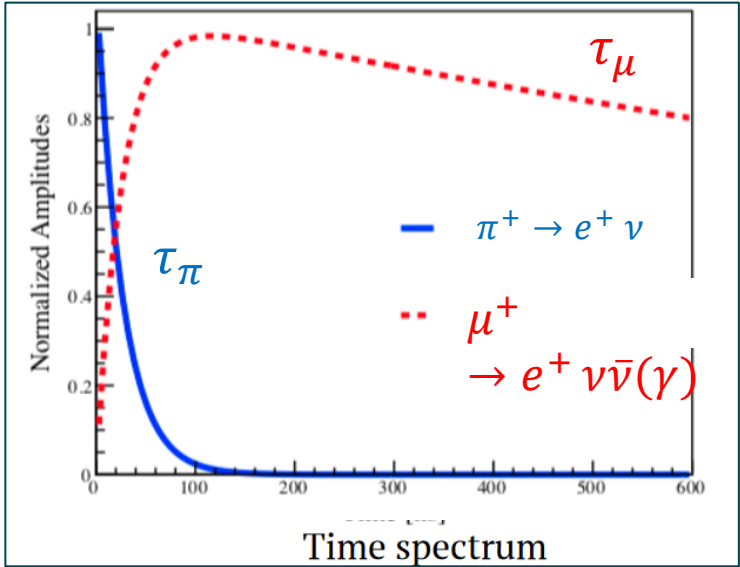
	m(MeV)	τ (ns)
π	139.6	26.03
μ	105.7	2197

Even with state-of-the-art CALO

- significant rad. tail for $\pi^+ \rightarrow e^+ \nu$
- time spectra remain powerful for separation of event types
- information beyond CALO critical to suppress background @ 10^{-4} precision



Peter



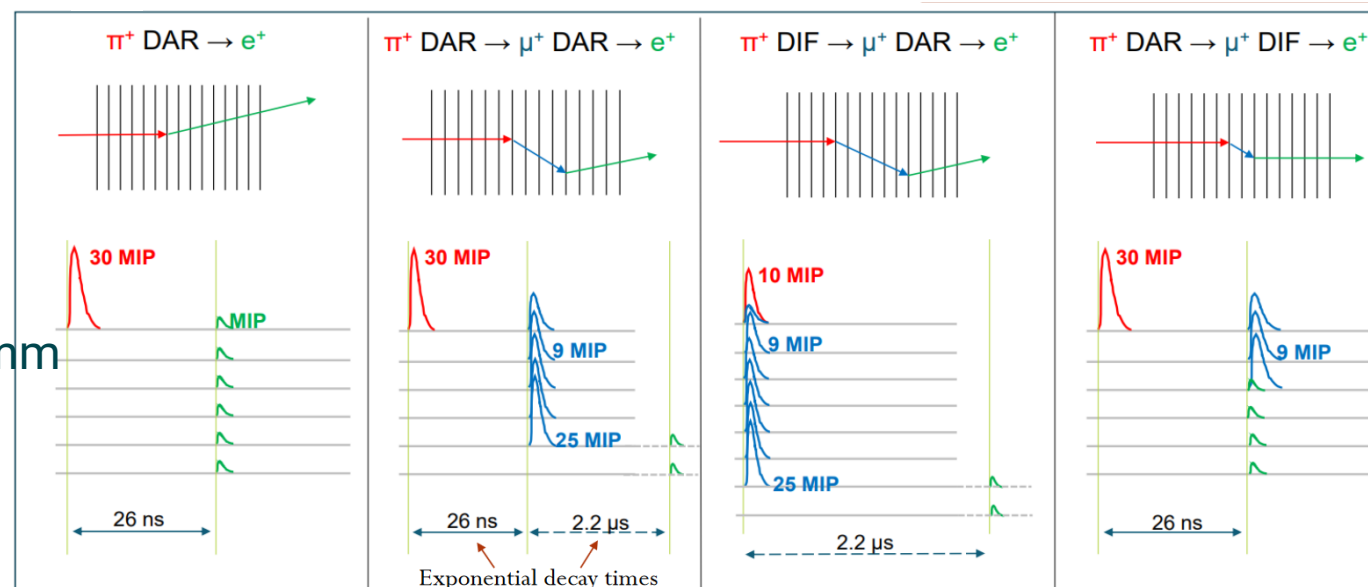
Spectra simplified, signals only, no background

Active Target ATAR 5-D tracker is key to separate events

Notation

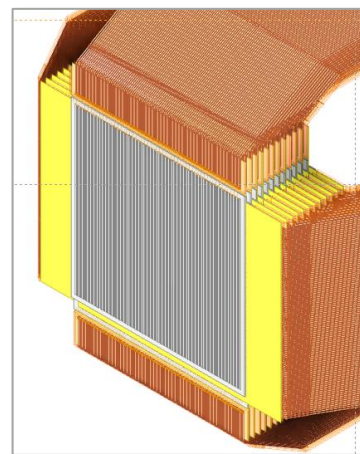
- DAR decay at rest
- DIF decay in flight

$$R_{\pi} \sim 4 \text{ mm}, R_{\mu} \sim 0.8 \text{ mm}$$



5-D tracker can provide rich information (x, y, z, t, E)

Baseline Technology
Low Gain Avalanche Diodes LGADs



• Specs

- dimensions
20 x 20 x 5.76 mm
48 sensor layers with
120 μm thickness, 200 μm strips
- t : $\Delta t \sim 200 \text{ ps}$, pulse pair 2 ns
- E : few 100 dynamic range, $\sigma_E < 10 \%$
- stack: fully active, “no: dead material

An Attempt of a Summary

Picosecond timing is at the front and center of all future HEP experiments and upgrades

- “plain” silicon sensors can reach 20ps timing resolution if the right (power hungry) preamplifier is used
- Internal avalanche amplification improves the SNR considerably, improving achievable time resolution
 - AC-LGADs are the best current candidate for true 4D tracking detectors for future experiments
- Future experiments of all sizes are already planning for AC-LGAD based detectors
- The future is here.